

ECE/CS 584: PVS Tutorial Part 1

Lecture 05

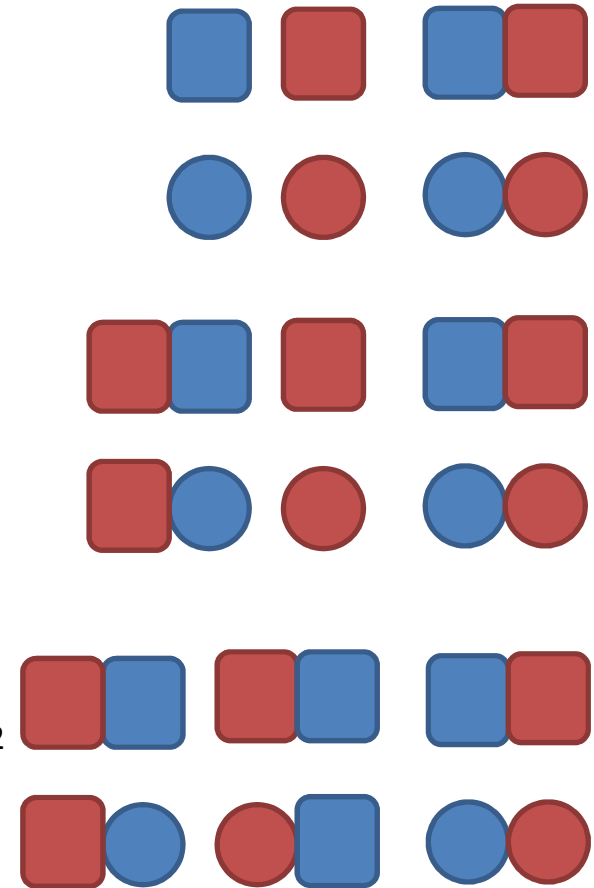
Sayan Mitra

Plan for Today

- Substitutivity final comments
- PVS tutorial Part 1

Recap

- Composition $\mathcal{A}_1 \parallel \mathcal{A}_2$
- α execution fragment of \mathcal{A} iff $\alpha_i = \alpha[(A_i, X_i)$ is an execution fragment of \mathcal{A}_i
- Traces $\mathcal{A} = \{ \beta \mid \beta \upharpoonright E_i \in \text{Traces } \mathcal{A}_i \}$
- **Theorem 1.** If $\mathcal{A}_1 \leq \mathcal{A}_2$ and $\mathcal{B}_1 \leq \mathcal{B}_2$
then $\mathcal{A}_1 \parallel \mathcal{B}_1 \leq \mathcal{A}_2 \parallel \mathcal{B}_2$.
- **Theorem 2.** If $\mathcal{A}_1 \parallel \mathcal{B}_2 \leq \mathcal{A}_2 \parallel \mathcal{B}_2$ and $\mathcal{B}_1 \leq \mathcal{B}_2$
then $\mathcal{A}_1 \parallel \mathcal{B}_1 \leq \mathcal{A}_2 \parallel \mathcal{B}_2$.
- **Conjecture.** If $\mathcal{A}_1 \parallel \mathcal{B}_2 \leq \mathcal{A}_2 \parallel \mathcal{B}_2$ & $\mathcal{A}_2 \parallel \mathcal{B}_1 \leq \mathcal{A}_2 \parallel \mathcal{B}_2$
then $\mathcal{A}_1 \parallel \mathcal{B}_1 \leq \mathcal{A}_2 \parallel \mathcal{B}_2$?

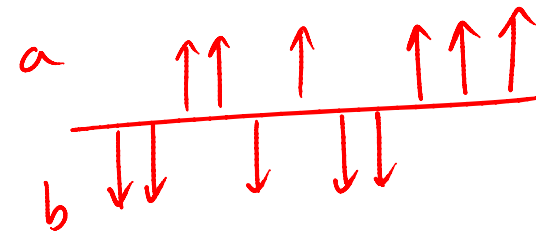


Fun with compositions

- 4 automata, all have the same external actions
a, b

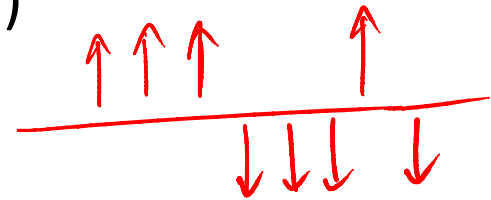
automaton CatchUpA

- external a, b
- states $\text{counta} : \text{Nat} := 0, \text{countb} : \text{Nat} := 0, \text{now} : \text{Real} := 0,$
 $\text{next} : \text{discrete Real} := 0$
- transitions
external a
pre ($\text{counta} \leq \text{countb}$) \wedge (now = next)
eff $\text{counta} := \text{counta} + 1; \text{next} := \text{now} + 1$
external b
eff $\text{countb} := \text{countb} + 1; \text{next} := \text{now} + 1$
- trajectories
stop when $\text{now} = \text{next}$
evolve $d(\text{now}) = 1$



automaton **CatchUpB**

- external a, b
- states $\text{counta} : \text{Nat} := 0, \text{countb} : \text{Nat} := 0, \text{now} : \text{Real} := 0,$
 $\text{next} : \text{discrete Real} := 0$
- transitions
- external b
- pre (**countb + 1** \leq counta) \wedge (now = next)
eff countb := countb + 1; next := now + 1
- external a
eff counta := counta + 1; next := now + 1
- trajectories
stop when now = next
evolve d(now) = 1



- CatchUpA can perform arbitrarily many b's and an a if $\text{count}_a \leq \text{count}_b$
- CatchUpB can perform arbitrarily many a's and a b if $\text{count}_a < \text{count}_b$
- **CatchUpA || CatchUpB** can perform arbitrarily many a's and b's

automaton BoundedAlternateA

external a, b

states myturn : Bool := true, maxout : Nat

transitions

- external b

 eff myturn := true

- external a

 pre myturn \wedge (maxout > 0)

 eff myturn := false ; maxout := maxout - 1

automaton BoundedAlternateB

external a, b

states myturn : Bool := false, maxout : Nat

transitions

- external a

 eff myturn := true

- external b

 pre myturn \wedge (maxout > 0)

 eff myturn := false ; maxout := maxout - 1

Putting it all together

- For a given value of maxout BoundedAlternateA performs a finite number of a's and arbitrarily many b's
- CatchUpA || BoundedAlternateB performs a finite number of alternating A's and B's
- BoundedAlternateA || BoundedAlternateB performs a finite number of alternating A's and B's
- CatchUpA || BoundedAlternateB \leq BoundedAlternateA
|| BoundedAlternateB
- CatchUpB || BoundedAlternateA \leq BoundedAlternateB
|| BoundedAlternateA
- But
- CatchUpA || CatchUpB $\not\leq$ BoundedAlternateA
|| BoundedAlternateB

Wrap-up for Hybrid Automaton Modeling Framework

- Nondeterministic state machines
- Abstract transitions and trajectories
- Synchronization through shared actions
 - Shared variables (used Hybrid I/O automata)
- Executions, Reachability, Traces
- Forward backward simulations
- Substitutivity